



Preliminary Feasibility Analysis of Component Based Modelling and Automatic Java Code Generation for Nanosatellite On-Board Software

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Overview

- Motivation
- Nanosat1B on board sw component model
- EDROOM
- Feasibility analysis of EDROOM to JEDROOM
- Achievements and future work

Motivation

- Nanosat1B (INTA) on-board sw was developed:
 - Graphical Component Modelling
 - Automatic C++ Code Generation
 - EDROOM CASE tool assists in this process
- Nanosat 2 (INTA) will be based on LEON arch
- Currently there is Java support for LEON (FijiVM)
- ¿Could we port EDROOM for Automatic Java Code Generation on LEON arch?
- ¿Is feasible the modelling and automatic java code generation of a Nanosatellite on-board sw?

Nanosat1B

Weight \approx 25 Kg

RAM: 1 Mb

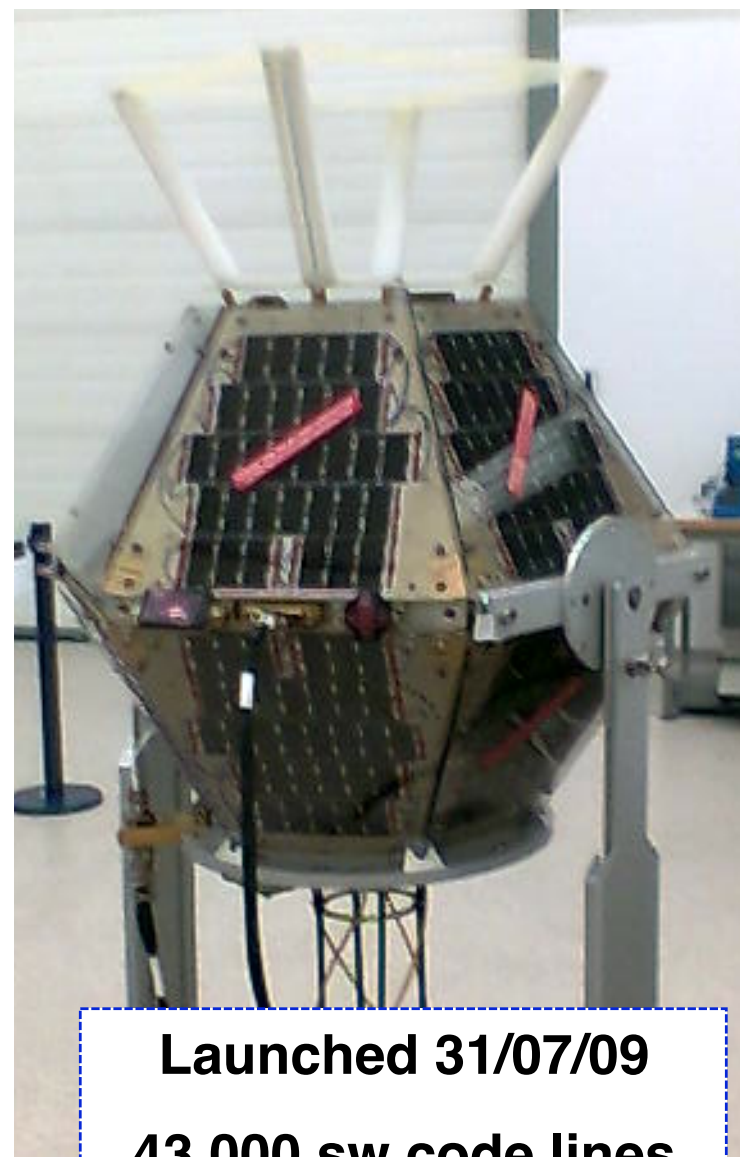
PROM: 256 Kb

EEPROM: 256 Kb

MMU: 4 Mbyte

CPU: μ c 68332

Clk: 16 MHz

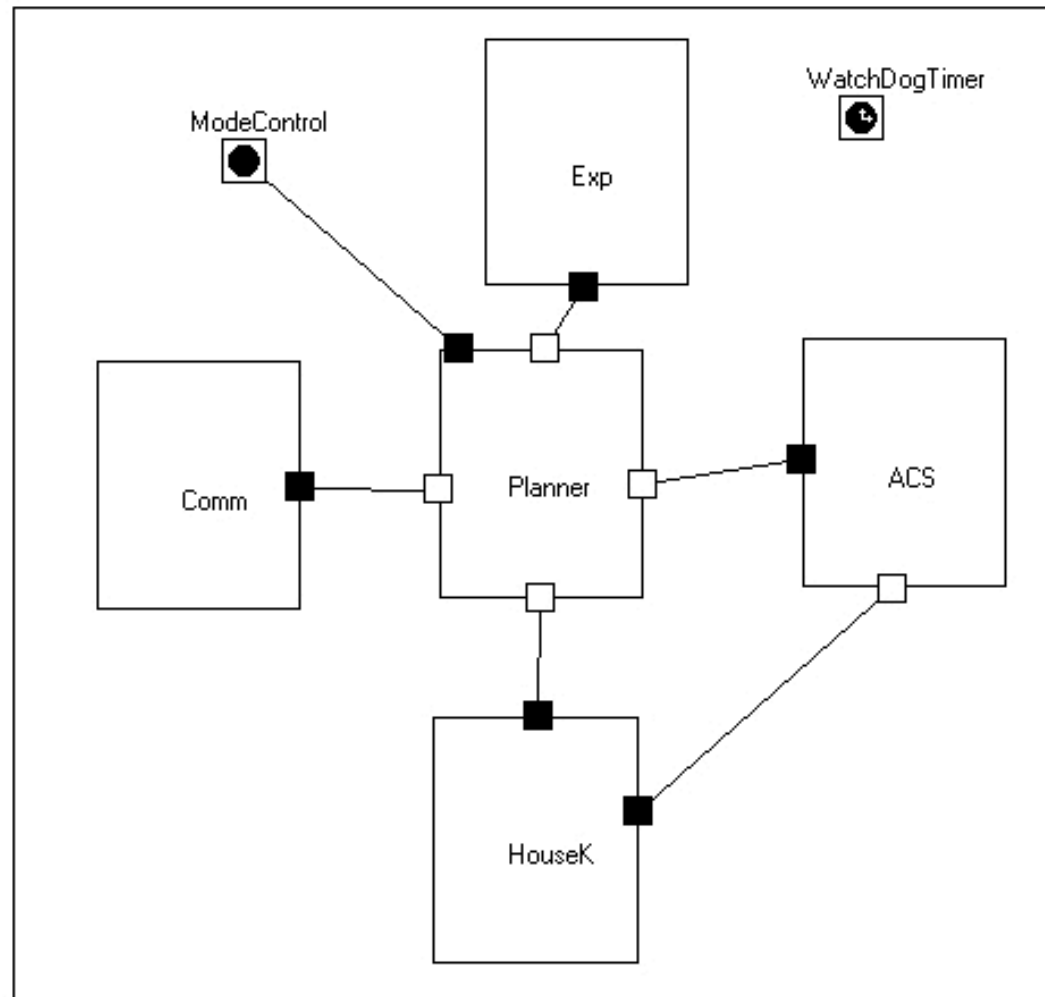


Launched 31/07/09

43.000 sw code lines

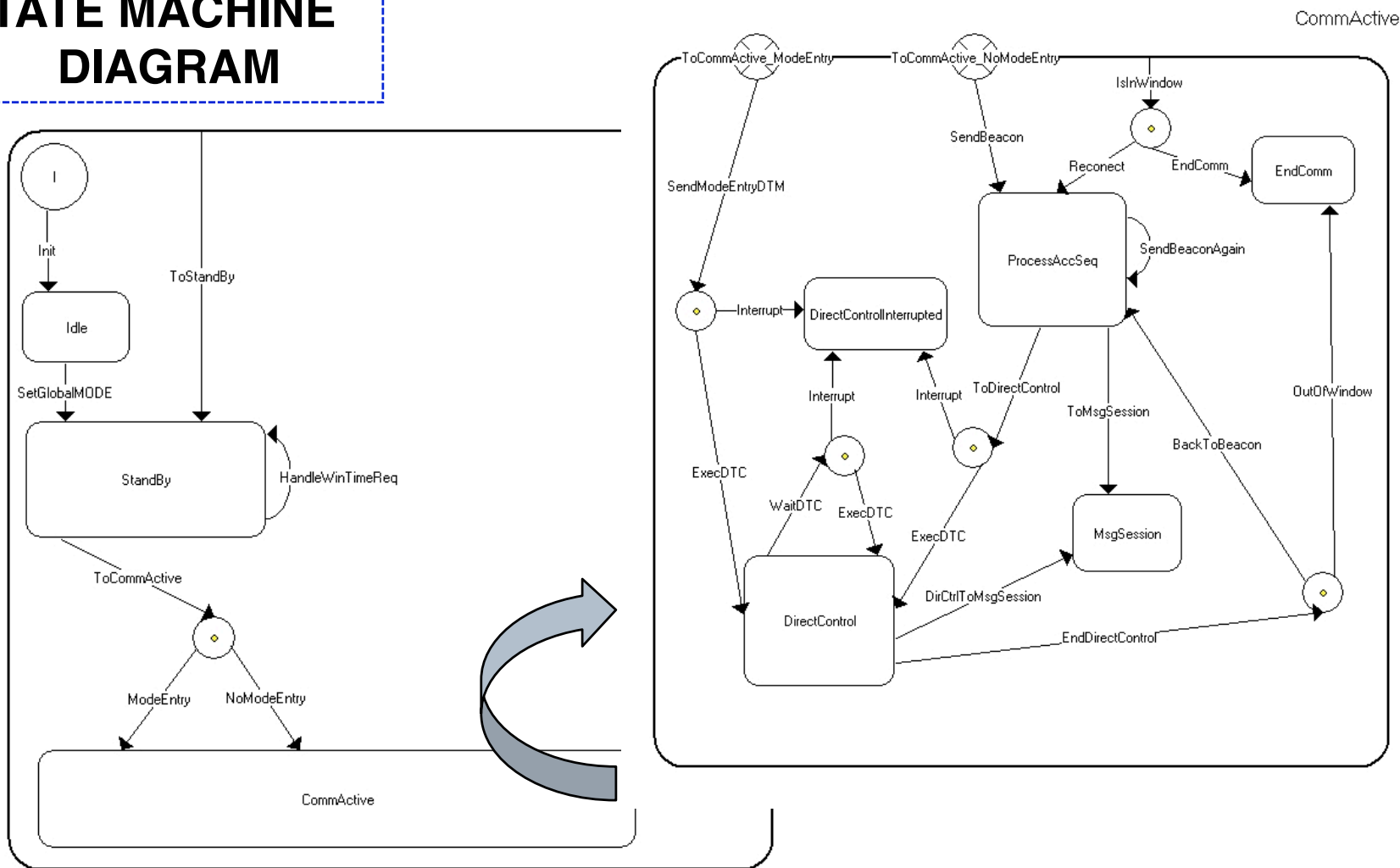
Nanosat1B Sw Component Model

SYSTEM COMPONENT DIAGRAM



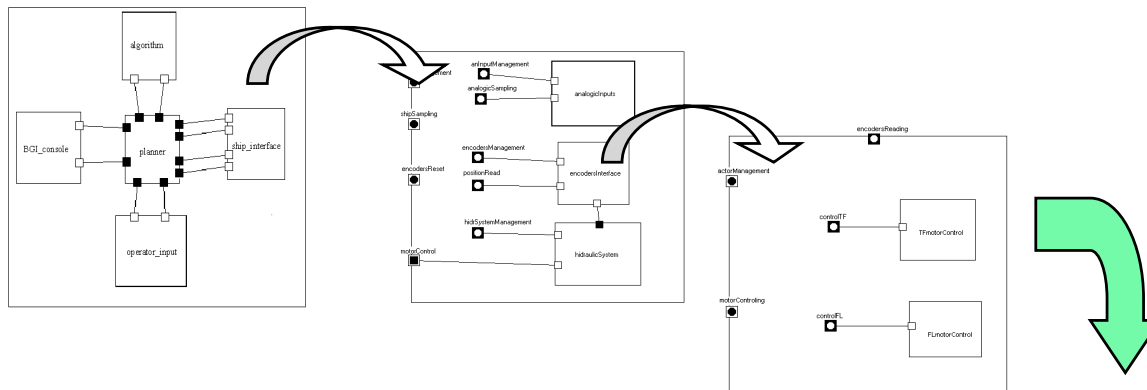
Nanosat1B Sw Component Model

STATE MACHINE DIAGRAM



EDROOM

1 Graphical definition of Structure and Communication



3 Detail level implementation

2 Behaviour Specification

4 Automatic Code Generation

```

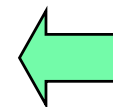
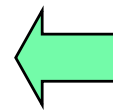
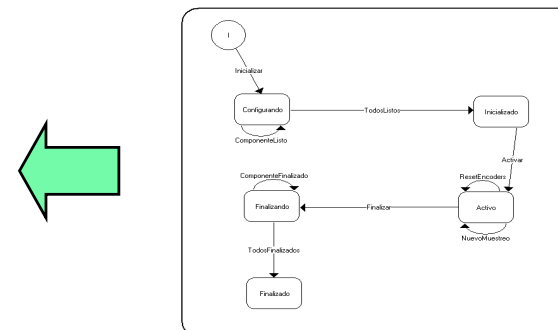
classDiagram
    class BCI_console
    class algorithm
    class planner
    class ship_interface
    class operator_input
    BCI_console --> algorithm
    BCI_console --> planner
    BCI_console --> ship_interface
    BCI_console --> operator_input
    
```

```

classDiagram
    class analogInputs
    class encoderInterface
    class habulaeSystem
    class encoderManagement
    class positionRead
    class motorControl
    class encoderReset
    class motorControl
    analogInputs --> encoderInterface
    encoderInterface --> habulaeSystem
    encoderManagement --> positionRead
    positionRead --> motorControl
    encoderReset --> motorControl
    motorControl --> motorControl
    
```

```

classDiagram
    class encoderReading
    class motorControlling
    class TFundorControl
    class TFundorControl
    encoderReading --> TFundorControl
    motorControlling --> TFundorControl
    
```



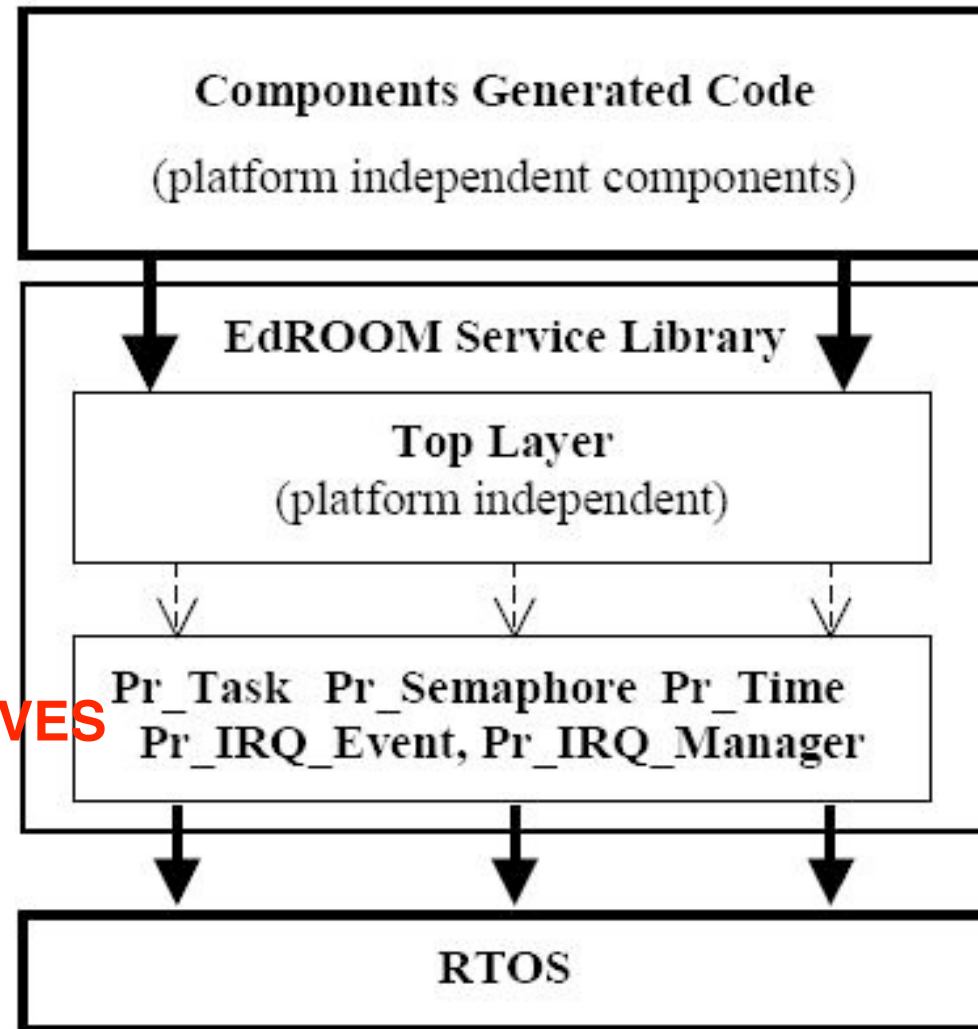
EDROOM

**AUTOMATIC CODE
GENERATOR**

**EDROOM SERVICE
LIBRARY**

REAL TIME

BASIC PRIMITIVES

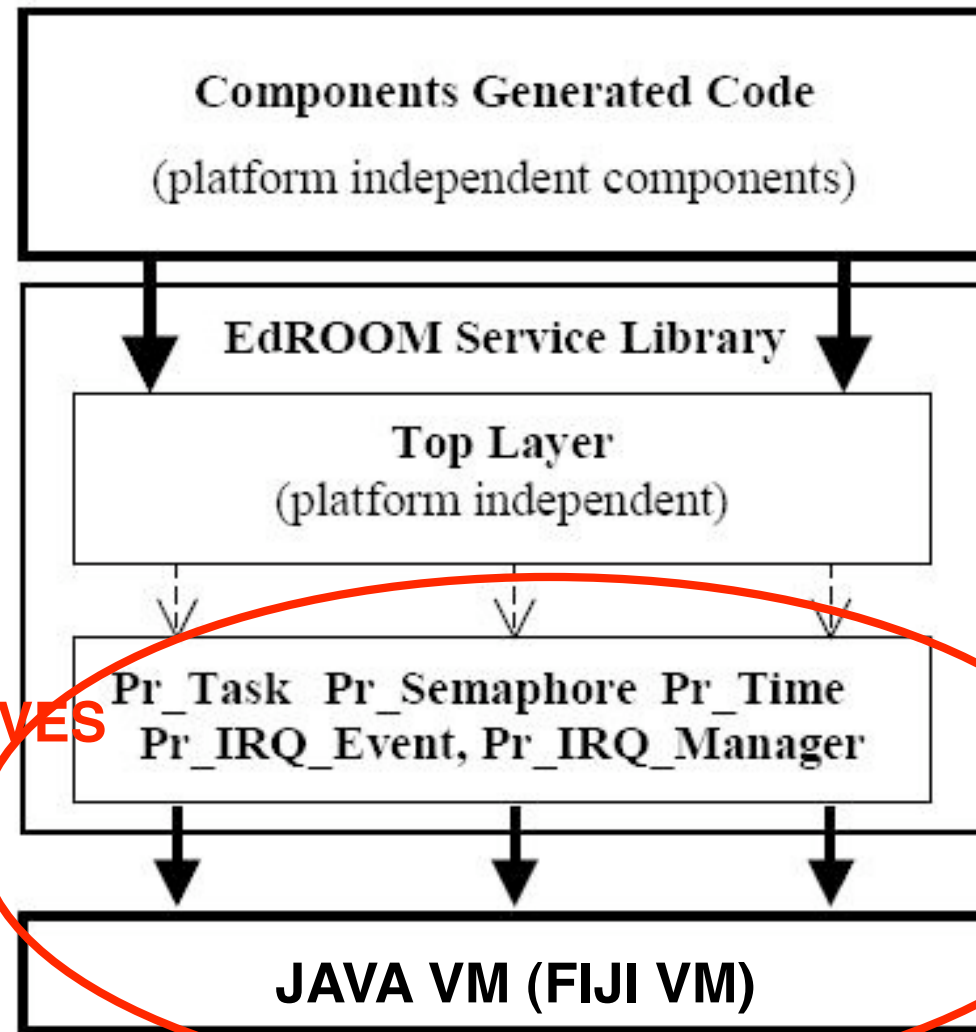


Feasibility Analysis of JEDROOM

JAVA CODE
GENERATION

JAVA EDROOM
SERVICE LIBRARY

REAL TIME JAVA



BASIC PRIMITIVES



JEDROOM Requirements

- Memory management:
 - ESL receives the memory for the main function, so it can be compatible with scoped memory, immortal memory or heap memory provided by Fiji VM.
- Mutual exclusion access:
 - ESL requires the definition of critical section free of priority inversion. Fiji VM can be configured with `--lock-impl pip` flag for providing priority inheritance to *synchronized* methods.

JEDROOM Requirements

- Dynamic thread priority configuration:
 - ESL component threads (`Pr_Task`) require their priority can be assigned to the most prioritized message received.
 - The Fiji VM package `com.fiji.fivm.ThreadPriority` provides the `setPriority` method of `Thread` class that can be applied in order to get this functionality.
- Counting semaphores:
 - ESL requires counting semaphores (`Pr_semaphore`) that can be implemented in Java using the standard primitives `notify` and `wait`



JEDROOM Requirements

- Timing:
 - ESL (Pr_Time) requires both absolute and relative delays.
 - The Fiji VM package *com.fiji.fivm.Time* provides the method *Thread.sleep* for relative delays, while *com.fiji.fivm.r1.fivmRuntime* provides *fivmRuntime.waitAbsolute* for absolute delays.

Achievements and Future Work

□ Achievements

- Port and Test the Basic Primitives over FijiVM

□ Future Work

- Port the upper layer of the ESL to Java
- Build a component based system as a simple example of use the Java ESL and FijiVM on LEON3
- Adapting the automatic code generation to the Java ESL
- Build a test bench to certify the whole product.
- Build a Java prototype of the Nanosat on board software running on LEON