

NSWI101: SYSTEM BEHAVIOUR MODELS AND VERIFICATION

LAB 07 – NuXMV

Jan Kofroň



FACULTY
OF MATHEMATICS
AND PHYSICS
Charles University

Department of
Distributed and
Dependable
Systems



- State-of-the-art symbolic model checker (recall: Spin is an explicit model checker)
- Based on NuSMV, extending it
- Originally developed at Carnegie Mellon University (SMV)
- Special input language, CTL properties
- Uses OBDDs for states' manipulation
- Both synchronous and asynchronous systems may be described

- *Parallel assignment language*
- In each step all variables are reassigned – possible issues of circular dependencies,
...
- Allows for easy OBDD modelling
- Initial and “next” values are specified

EXAMPLE I.

```
MODULE main
VAR
  request : boolean;
  state : {ready, busy};
ASSIGN
  init(state) := ready;
  next(state) := case
    state = ready & request : busy;
    TRUE : {ready, busy};
  esac;
SPEC
  AG(request -> AF state = busy)
```

EXAMPLE II.

```
MODULE counter_cell(carry_in)
VAR
  value : boolean;
ASSIGN
  init(value) := FALSE;
  next(value) := value xor carry_in;
DEFINE
  carry_out := value & carry_in;

MODULE main
VAR
  bit0 : counter_cell(TRUE);
  bit1 : counter_cell(bit0.carry_out);
  bit2 : counter_cell(bit1.carry_out);
SPEC AF(bit2.carry_out)
```

- boolean
- enum
- word – specifying bit width:
 - e.g. `word[3]` – three-bit range, i.e., 0–7
 - Cannot create unions thereof – use integer sets instead
- integer
- real – rational numbers!
- arrays, wordarrays, intarrays (unbounded arrays) – nesting of types
- sets – limited, just sets of boolean, integer, symbolic and mixed enums

- Propositional way of specification
- FAIRNESS – a fairness constraint, mostly used with running
- INIT – initial value of local variables
- TRANS – definition of transition relation, e.g.:
 - $\text{next}(\text{output}) = !\text{input} \mid \text{next}(\text{output}) = \text{output}$
- INVAR – conditions restricting valid states

- Use of INIT, TRANS and INVAR NOT recommended as “Logical absurdities (...) can lead to unimplementable descriptions” resulting in systems with no transitions, etc.
- However, it may be flexible when translating from other languages to SMV

DEFINE

- DEFINE – symbols definition
- Does not introduce new variable, just new symbol

DEFINE

```
start := state = 0 & timeout;  
finish := state = 3;  
request := case  
    state = 0: 0;  
    TRUE : 1;  
esac;
```


- Encapsulation of a group of declarations
- Can be parametrized when reusing
- Can contain instances of other modules
- Example: see above
- A parameterless main module has to be in each program

- Properties of models can be verified via `nuxmv model.smv`
All CTL properties specified inside the models are checked
- Model can be simulated via `nuxmv -int model.smv`
– interactively, randomly, or deterministically

- `nuXmv -int model.smv` – starts the nuXMV in interactive model
- `go` – prepares the model
- `pick_state -r` – picks up initial state (-r randomly, -i interactively)
- `print_current_state -v` – prints the current state (-v verbosely)
- `simulate -r -k 3` – simulates randomly three steps

- The original tool and manual downloadable at <http://www.cs.cmu.edu/~modelcheck/smv.html>
- Implementations to use: NuSMV and **NuXMV**:
 - <http://nusmv.fbk.eu/>
 - <http://nuxmv.fbk.eu/>
- NuXMV is newer and recommended, documentation: <https://es.fbk.eu/tools/nuxmv/downloads/nuxmv-user-manual.pdf>