

Verifying the Top-Down Solver in Isabelle

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Constraint Systems

$$\mathbb{D} := 2^{\{a,b,c\}}, \sqsubseteq := \subseteq$$

$$y \sqsupseteq \{a\} \cup z$$

$$z \sqsupseteq y \cup w$$

$$w \sqsupseteq \{c\}$$

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Solve a system of inequalities:

$$x_i \sqsupseteq f_i(x_1, \dots), \quad i = 1, \dots$$

The Top-Down Solver

Recursive evaluation:

- ▶ starts with an interesting unknown
- ▶ descends to **query** influencing unknowns in right-hand side
- ▶ **iterates** on a queried unknown until local fixpoint is found

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Self-observation:

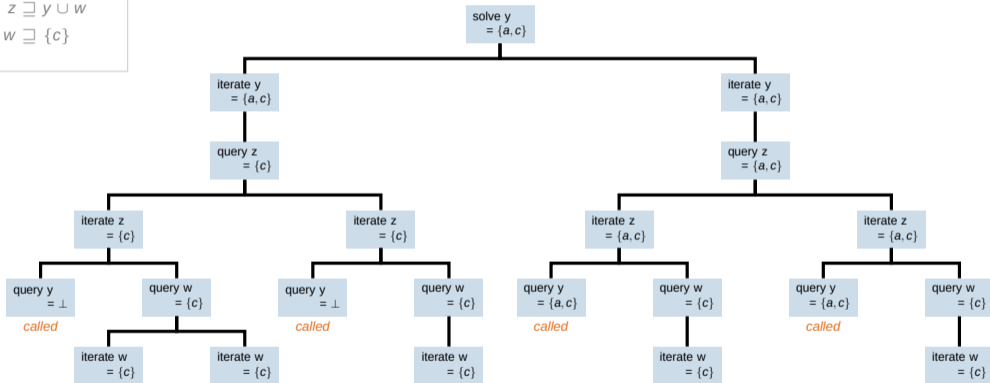
- ▶ map σ from unknowns to their last evaluated value
- ▶ set of **called** unknowns: to detect recursive dependencies
- ▶ set of **stable** unknowns: value can be looked up without re-iteration
- ▶ map of **influenced** unknowns: re-evaluate when value changes

The Trace of the Solver

$y \sqsupseteq \{a\} \cup z$

$z \sqsupseteq y \cup w$

$w \sqsupseteq \{c\}$



Proving Partial Correctness

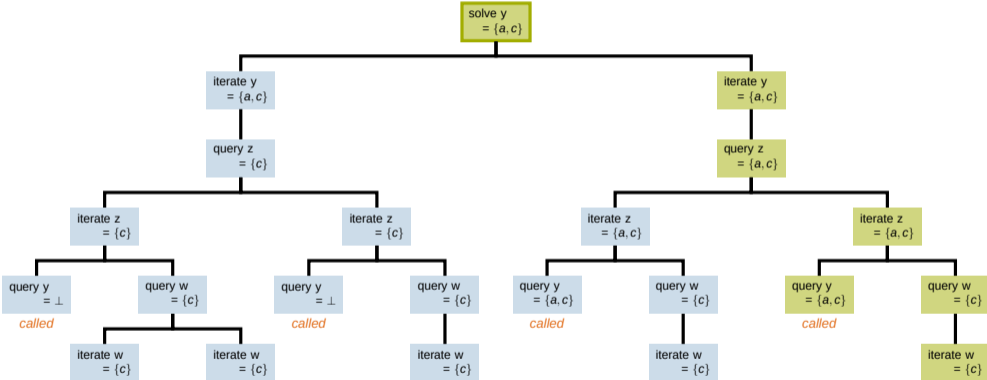
call to solve terminates and $\text{solve } x = (xd, \sigma)$



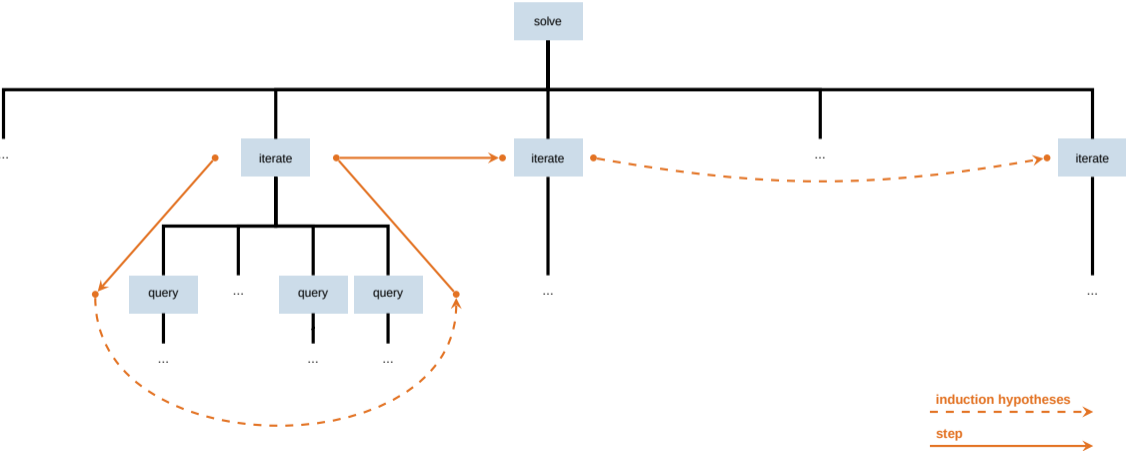
$\forall y \in \text{reach } x. \text{ eq } y \sigma = \sigma y$

reach: set of unknowns evaluated during the final iteration

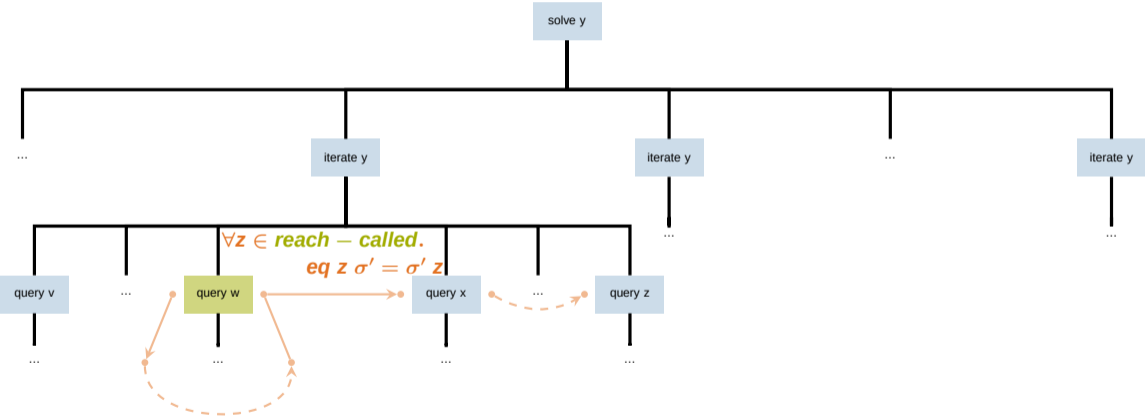
Reach



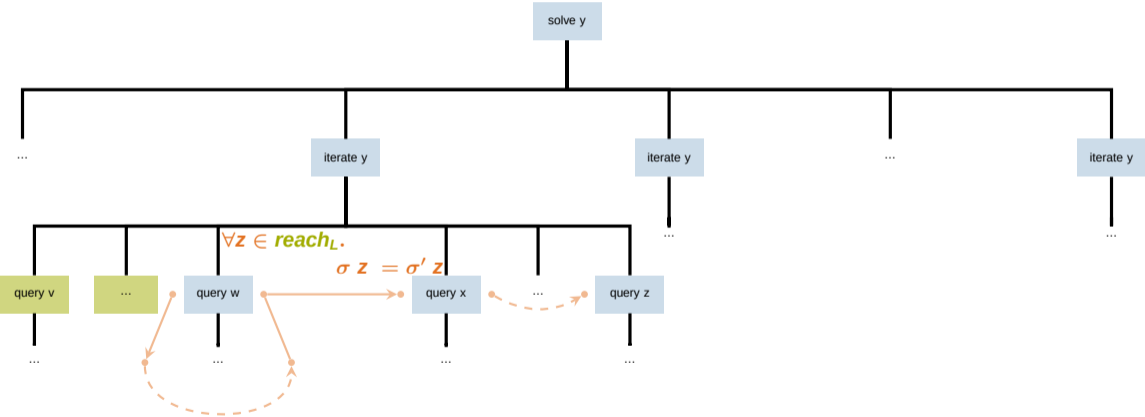
Induction over the Trace



Invariants



Invariants

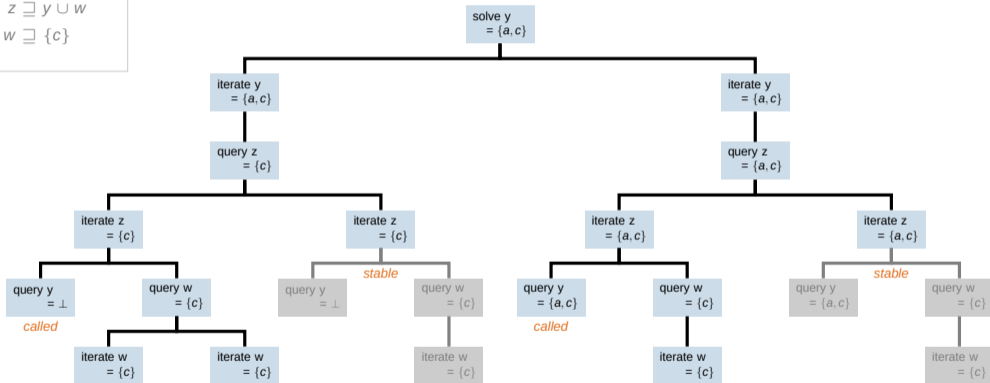


Ongoing Work: Record Stable Unknowns

$$y \sqsupseteq \{a\} \cup z$$

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$$w \sqsupseteq \{c\}$$



Summary

- ▶ formalized the top-down solver in Isabelle
- ▶ proved partial correctness for the simplified Top-Down Solver
 - ▶ by induction over trace
 - ▶ with invariants about its state of computation
- ▶ ongoing: show equivalence to vanilla Top-Down Solver

The Top-Down Solver - simplified

```
solve x = iterate x {x} empty_map
```

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solve x = iterate x {x} empty_map  
query (Answer d) called  $\sigma = (d, \sigma)$   
query (Query x f) called  $\sigma = ($ 
```

```
iterate x called  $\sigma = ($ 
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solve x = iterate x {x} empty_map
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query (Query x f) called  $\sigma = ($ 
  let (xd,  $\sigma$ ) =
    if  $x \notin$  called then
      iterate x (insert x called)  $\sigma$ 

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iterate x called  $\sigma = ($ 
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